

Business from technology

Properties and Calibration of MEMS and Piezoactuated Fabry-Perot Spectral Imagers

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VTT TECHNICAL RESEARCH CENTRE OF FINLAND

Outline

- Introduction and classification of imaging spectrometers
- Overview of the VTT Fabry-Perot Interferometer (FPI) technologies
- Fabry-Perot Interferometer principle and spectroscopy applications
- FPI hyperspectral imager major characteristics and operation modes
- The Piezo-actuated FPI component and its controlling
- VTT's Surface Micro-Machined MEMS FPI Structure
- World's first MEMS FPI Spectral Imager
- VTT UAS FPI VIS-VNIR Spectral Camera for forest and agriculture applications
- **FPI based spectral camera F-number and throughput**
- Mathematical description of the FPI Spectral Imager concept
- Calibration of the FPI Hyperspectral Imager
- Conclusions and future plans
- Additional slides on the-state-of-the-art of the hyper and multispectral imaging technology and on planned UAV applications of FPI spectral imager

Classification of imaging spectrometers for remote sensing applications

Ref. X. Prieto-Blanco, C. Montero-Orille, B. Couce, R. de la Fuente, "Optical configurations for Imaging Spectrometers, Comput. Intel. For Remote Sensing, SCI 133, pp. 1- 25, 2008 Springer-Verlag, Heidelberg 2008.

Ref. R. Sellar&G. Boreman, "Classification of imaging spectrometers for remote sensing applications", Opt.Eng. 44(1), Jan 2005.

Overview of the VTT Fabry-Perot Interferometer – technologies

Microelectromechanical components (MEMS)

- Development started 1990 / 1991, CARBOCAP® -production at Vaisala / VTT 1997
- Novel technologies: ALD, Si_3N_4 , etc.
- Small, robust, cheap, high volumes
- Wavelength ranges 350 nm 14000 nm

Piezo-components

- More transmitted light, large range of wavelengths
- Small and medium series with apertures from 3 mm to 50 mm.
- Fits well to imaging systems
- VTT owns IPR of several Fabry-Perot inventions

Piezo-actuated Fabry-Perot interferometer modules

Detector modules including a Fabry-Perot interferometer detector and optionally cooling.

Filter chips, 3x3 mm²

Tunable bandpass filters (350 – 14000 nm)

Fabry-Perot Interferometer and Spectroscopy

- Interference created by two reflective surfaces
- **Usage: Tunable band-pass filter**

Fabry-Perot Interferometer (FPI) and principle of hyperspectral imaging based on it

FPI multispectral image sensor hyperspectral imager principle - Matching three Fabry-Perot Interferometer orders to a R-, G-, and B-pixels

Transmission of the Fabry-Perot Interferometer at air gap value of 1100 nm

400 500 600 700 800 900 1000 1100 $^{9}_{400}$ 0.1 0.2 0.3 Wavelength/[nm]

Quantum efficiency

Quantum efficiency

- Red/R pixels

Combined Quantum efficiency of the Fabry-Perot Interferometer at air gap 1100 nm and the CMOS RGB image sensor MT009V022

FPI hyperspectral imager major characteristics

FPI hyperspectral imager operation modes

- Tunable FPI filter camera utilizing only one FPI order at a time for example VNIR camera for 700 – 1000 nm with air gap range 520 – 880 nm, res. 9..11 @ FWHM or Vis-VNIR camera for 550 – 770 nm air gap range 360 – 560 nm, res. 12..15 @ FWHM
- **False color imager with relatively narrow** Green, Red and VNIR pass bands with +5 Mpix resolution (see next slide)
- **The FPI camera can be used as a** tunable multispectral imager with +5 Mpix resolution by taking images in sequence at the selected spectral bands. Three 5 Mpix images can be recorded in typically in less than 0.3 s.

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False color imager with relatively narrow Green, Red and VNIR pass bands

- The FPI spectral camera operates like a normal false color camera except the green (G), red (R) and VNIR spectral bands are narrower.
- An example of the measured spectral transmissions of the FPI module at air gap values of 1000 nm and 1500 nm are shown on the right.
- The spectral bands used in the false color imaging at the air gap value 1500 nm are:
	- G: 560 nm @ 10 nm FWHM
	- R: 670 nm @ 10 nm FWHM
	- VNIR: 845 nm @ 10 nm FWHM

Measured transmission at air 1500 nm gap

The Piezo-actuated Fabry-Perot Interferometer component and its controlling

Fused silica substrate

Hermetically packaged Piezo actuated FPI

Commercial piezo-actuators

=> FPI cavity stays parallel

Piezo Actuated Fabry-Perot Interferometer control electronics

VTT's Surface Micro-Machined MEMS FPI Structure

Upper mirror acts as a tensioned membrane \rightarrow enables:

- **Large optical apertures up to millimeters in diameter**
- Superior mirror flatness
- Very high nominal frequencies, \sim 1 MHz (insensitive to vibrations)
- No gravitational effects
- **Low operation voltages**

World's first MEMS FPI Spectral Imager

- VTT has built world's first MEMS FPI based spectral imager device for demonstration to Photonics West 2011 fair
- **The device consist of optics, a** packaged MEMS Fabry-Perot Interferometer (aperture diameter 2 mm), and a color imager, together with electronics and mechanics.
- **Device can be used for surface** inspection (it has built-in white LEDs as light source) or in remote sensing mode, focused to infinity
- **The wavelength range is 460-585 nm** and resolution ca. 5 nm

FPI Spectral Imager trials with the UAV helicopter

- VTT has developed in previous VTT and Tekes funded projects proprietary hyperspectral imaging technology for light weight UAS planes (Patents: FI119345B , GB 2445956, Pat. Appl. FI20095356).
- A proof of concept prototype has been built and used in VITO (Flemish Institute for Technological Research) Draganfly X6 UAS helicopter.
- The results of the first trial flights has been published in SPIE conferences on September 2009¹ and April 2010².

¹Saari, H., Aallos, V., Akujärvi, A., Antila, T., Holmlund C., Kantojärvi, U., Mäkynen, J. and Ollila J., "Novel Miniaturized Hyperspectral Sensor for UAV and Space Applications", Proc. SPIE 7474 (2009).

²Saari, H., Aallos, V., Holmlund, C., Mäkynen, J., Delauré, B., Nackaerts, K., and Michiels, B., "Novel Hyperspectral Imager for Lightweight UAVs", Proc. SPIE 7668 (2010) to be published.

VTT proof-of-concept prototype integration to the Draganfly X6 UAS helicopter

VTT proof-of-concept prototype used for test targets onboard Draganfly X6 UÁS helicopter

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VTT UAS FPI VIS-VNIR Spectral Camera for forest and agriculture applications

Major specifications of the spectral camera **Spectral range:** 500 – 900 nm **Spectral Resolution:** 7..10 nm @ FWHM **Focal length:** 9.3 mm **Image size:** 7.1 mm x 4.3 mm, 5 Mpix **Field of View:** 32° (across the flight direction) **Ground pixel size:** 3.5 cm @ 150 m height **Weight:** 395 g **Size:** 62 mm x 61 mm/76mm x 120 mm **Power consumption:** 3 W

 95

105 120

76

FPI based spectral camera F-number and throughput 1(4)

An ideal lens with focal length of f_{lens1} collimates the rays coming from an object with a height h_{im} and the angle of the collimated beam is θ_{max} . In the case of relay optics at magnification of 1 the $h_{\text{im}} = h_{\text{cmos}}$ which is the maximum radial height of the image sensor. It is now possible to calculate the focal length of the Lens 1

$$
f_{Lens1} = \frac{h_{cross}}{\tan(\theta_{max})}
$$
 Eq. 1

The maximum effective aperture of the lens 1 can be approximated by the effective diameter of the FPI module D_{FPI} . The F-Number of the FPI spectral camera Fn_{svs1} is given by

FPI based spectral camera F-number and throughput 2(4)

- It is possible to lower the Fnumber by using a larger FPI diameter and by increasing the max allowed FPI ray angle.
- The F-number as low as 1.0 can be achieved with 15 mm FPI diameter and 10 degree max FPI angle.
- **This makes it possible to** manufacture Hyperspectral imager with weight < 400 g for Vis-VNIR with F-number 1.0 and spectral resolution < 10 nm @ FWHM

Diameter of the Fabry-Perot Interferometer/[mm]

max allowed FPI angle 5.0 degree, Image diameter $= 7.13$ mm max allowed FPI angle 7.5 degree, Image diameter $= 7.13$ mm max allowed FPI angle 10.0 degree, Image diameter $= 7.13$ mm

-
- max allowed FPI angle 15.0 degree, Image diameter $= 7.13$ mm

FPI based spectral camera F-number and throughput 3(4)

FPI ray angle 7.5 degrees FPI ray angle 10 degrees -FPI ray angle 15 degrees

• The FPI ray angle affects the center wavelength of the FPI spectral peak. In the first approximation the peak wavelength is linearly dependent on the cosine of the ray angle.

$$
\lambda_0 = \frac{m \cdot d \cdot \cos(\theta)}{2} \quad , \text{ m=1,2...}
$$

- The optics can be designed in such a way that the rays go through the FPI as a collimated beam for a specific pixel of the image.
- So for the measurement of continuous spectrum the large FPI ray angles can be used because the spectral resolution is not affected by the FPI ray angle

FPI based spectral camera F-number and throughput conclusions 4(4)

- **The lowest F-numbers for existing push broom** instruments are in the range 2.0….2.8 and the average transmission of the spectrograph is around 50% with peak transmission 70..80%.
- The FPI spectral imager average transmission with metal mirrors is around 25 % and 80 % with dielectric mirrors and lowest F-number in the range 1.0…1.8.

The throughput of FPI spectral imager can be higher than the throughput of push broom instruments if continuous spectrum is to be measured.

Signal of a RGB image sensor Blue (B), Green (G) and Red (R) pixels

Equations for the calculation of the signals of a RGB image sensor Blue (B), Green (G) and Red (R) pixels

$$
S_B(d_{gap}) = \int_{\lambda_{min}}^{\lambda_{max}} \eta_B(\lambda) T_{FPI}(\lambda, d_{gap}) T_{sys}(\lambda) S(\lambda) d\lambda
$$
 (5)

$$
S_G(d_{gap}) = \int_{\lambda_{min}}^{\lambda_{max}} \eta_G(\lambda) T_{FPI}(\lambda, d_{gap}) T_{sys}(\lambda) S(\lambda) d\lambda
$$
 (6)

$$
S_R(d_{gap}) = \int_{\lambda_{min}}^{\lambda_{max}} \eta_R(\lambda) T_{FPI}(\lambda, d_{gap}) T_{sys}(\lambda) S(\lambda) d\lambda
$$
 (7)

 $\eta_{\rm B}(\lambda)$, $\eta_{\rm G}(\lambda)$ ja $\eta_{\rm R}(\lambda)$ are the quantum efficiences of the B-, G- ja R-pixels at the wavelength λ and the $S(\lambda)$ is the spectral photon flux entering the system. The combined spectral transmission of the optical system without the FPI is included in the term $T_{sys}(\lambda)$.

Retrieval of the spectral signals at the Fabry-Perot Interferometer pass bands at the selected three orders 1(3)

 For the retrieval of the spectral signal a calibration is required for the responses of the B-, G- and R-pixels around the selected three FPI pass bands.

$$
S_{Bn}(d_{gap}, n) = \int_{2 \cdot d_{gap} \cdot (\frac{1}{n} + \frac{1}{2 \cdot n \cdot (n-1)})}^{\infty} \int_{2 \cdot d_{gap} \cdot (\frac{1}{n} - \frac{1}{2 \cdot n \cdot (n+1)})}^{\infty} \int_{2 \cdot d_{gap} \cdot (\frac{1}{n} - \frac{1}{2 \cdot n \cdot (n+1)})}^{\infty} \int_{2 \cdot d_{gap} \cdot (\frac{1}{n} + \frac{1}{2 \cdot n \cdot (n-1)})}^{\infty} \int_{2 \cdot d_{gap} \cdot (\frac{1}{n} + \frac{1}{2 \cdot n \cdot (n-1)})}^{\infty} \int_{2 \cdot d_{gap} \cdot (\frac{1}{n} - \frac{1}{2 \cdot n \cdot (n+1)})}^{\infty} \int_{2 \cdot d_{gap} \cdot (\frac{1}{n} + \frac{1}{2 \cdot n \cdot (n+1)})}^{\infty} \int_{2 \cdot d_{gap} \cdot (\frac{1}{n} + \frac{1}{2 \cdot n \cdot (n-1)})}^{\infty} \int_{Rn}(d_{gap}, n) = \int_{Rn}^{2} \int_{Rn}(\lambda) T_{FP}(\lambda, d_{gap}) T_{sys}(\lambda) d\lambda
$$

 $\cdot n \cdot (n +$

 $2 \cdot n \cdot (n+1)$

 $\cdot d_{\text{gen}} \cdot (\frac{1}{1} - \frac{1}{1})$

n n n

 $2 \cdot d_{\text{gen}} \cdot (1 - 1)$

d gap

 d_{gan} is the FPI air gap width, n is the FPI order, the $\eta_B(\lambda)$, $\eta_G(\lambda)$ ja $\eta_R(\lambda)$ are the quantum efficiences of the B-, G- ja R-pixels at the wavelength λ , $T_{FPI}(\lambda, d_{\text{gan}})$ is the spectral transmission of the FPI and $T_{sys}(\lambda)$ is the combined spectral transmission of the optical system without the FPI.

Retrieval of the spectral signals at the Fabry-Perot Interferometer pass bands at the selected three orders 2(3)

In a measurement the goal is to determine the spectral intensity $S(\lambda)$ of the light At a preset gap width we will measure signals S_{Bm} , S_{Gm} and S_{Rm} . at the B-, G- ja R pixels The calibration coefficients S_{Bn} , S_{Bn+1} , S_{Bn+2} , S_{Gn} , S_{Gn+1} , S_{Gn+2} , S_{Rn} , S_{Rn+1} ja S_{Rn+2} can now be used for the calculation of the measured signals at the three narrow bands of three Fabry-Perot orders. The measured signals of the light at the three FPI passbands are now

$$
\begin{bmatrix} S_{Bn+2} & S_{Bn+1} & S_{Bn} \ S_{Gn+2} & S_{Gn+1} & S_{Gn} \ S_{Rn+2} & S_{Rn+1} & S_{Rn} \end{bmatrix} \cdot \begin{bmatrix} S_{n+2} \ S_{n+1} \ S_{n+1} \ S_{n} \end{bmatrix} = \begin{bmatrix} S_{Bm} \ S_{Gm} \ S_{Rm} \end{bmatrix}
$$

Where S_{n+2} , S_{n+1} and S_n are the unknown intensities at FPI orders $n+2$, $n+1$ and n.

The unknown can now be solved by

$$
\begin{bmatrix} S_{n+2} \\ S_{n+1} \\ S_n \end{bmatrix} = \begin{bmatrix} S_{Bn+2} & S_{Bn+1} & S_{Bn} \\ S_{Gn+2} & S_{Gn+1} & S_{Gn} \\ S_{Rn+2} & S_{Rn+1} & S_{Rn} \end{bmatrix}^{-1} \begin{bmatrix} S_{Bm} \\ S_{Gm} \\ S_{Rm} \end{bmatrix}
$$

Retrieval of the spectral signals at the Fabry-Perot Interferometer pass bands at the selected three orders 3(3)

The coefficients that must be applied to signals at B-, G- and R-pixels to get the signal at the selected air gap value are given by R matrix below

$$
\begin{bmatrix} R_{Rn+2} & R_{Gn+2} & R_{Bn+2} \ R_{Rn+1} & R_{Gn+1} & R_{Bn+1} \ \end{bmatrix} = \begin{bmatrix} S_{Rn+2} & S_{Rn+1} & S_{Rn} \ S_{Gn+2} & S_{Gn+1} & S_{Gn} \ S_{Bn+2} & S_{Bn+1} & S_{Bn} \end{bmatrix}^{-1}
$$

The signal at the FPI order n+2 as a linear combination of the signals at B-, G- and R-pixels

The signal at the pass band of the FPI order n+2 is a linear combination of the signals at B-, G- and R-pixels.

 $S_{n+2} = R_{Rn+2} \cdot S_{Rm} + R_{Gn+2} \cdot S_{Gm} + R_{Bn+2} \cdot S_{Bm}$

$$
S_{n+2} = R_{Rn+2} \cdot \int_{\lambda_{\min}}^{\lambda_{\max}} \eta_R(\lambda) T_{FPI}(\lambda, d_{gap}) T_{sys}(\lambda) \Phi_{ph}(\lambda) d\lambda + R_{Gn+2} \cdot \int_{\lambda_{\min}}^{\lambda_{\max}} \eta_G(\lambda) T_{FPI}(\lambda, d_{gap}) T_{sys}(\lambda) d\lambda + R_{Bn+2} \cdot \int_{\lambda_{\min}}^{\lambda_{\max}} \eta_G(\lambda) T_{FPI}(\lambda, d_{gap}) T_{sys}(\lambda) d\lambda + R_{Bn+2} \cdot \int_{\lambda_{\min}}^{\lambda_{\max}} \eta_R(\lambda) T_{FPI}(\lambda, d_{gap}) T_{sys}(\lambda) \Phi_{ph}(\lambda) d\lambda
$$

$$
S_{n+2} = \int_{\lambda_{\min}}^{\lambda_{\max}} (R_{Rn+2} \cdot \eta_R(\lambda) + R_{Gn+2} \cdot \eta_G(\lambda) + R_{Bn+2} \cdot \eta_B(\lambda)) \cdot T_{FPI}(\lambda, d_{gap}) T_{sys}(\lambda) \Phi_{ph}(\lambda) d\lambda
$$

Calibration of the FPI Hyperspectral Imager 1(5)

The calibration should provide as an output the spectral response curves

 $\eta_R(\lambda) \cdot T_{FPI}(\lambda, d_{\text{gap}}) \cdot T_{\text{sys}}(\lambda), \eta_G(\lambda) \cdot T_{FPI}(\lambda, d_{\text{gap}}) \cdot T_{\text{sys}}(\lambda), \eta_B(\lambda) \cdot T_{FPI}(\lambda, d_{\text{gap}}) \cdot T_{\text{sys}}(\lambda)$

These curves are used in the calculation of the calibration coefficients S_{Bn} , S_{Bn+1} , S_{Bn+2} , S_{Gn} , S_{Gn+1} , S_{Gn+2} , S_{Rn} , S_{Rn+1} and S_{Rn+2} .

The coefficients R_{Bn+1} , R_{Bn+2} , R_{Gn} , R_{Gn+1} , R_{Gn+2} , R_{Rn} , R_{Rn+1} and R_{Rn+2} are derived as an inverse matrix of S-coefficients.

The R-coefficients can be used in the calculation of photon flux at the three spectral bands of FPI orders n+2, n+1 and n.

Calibration of the FPI Hyperspectral Imager 2(5)

•The calibration is started with the measurement of the spectral photon flux entering the input of the FPI spectral imager.

•The signals of the absolute radiometer and the reference detector are typically recorded for wavelength ranges 400 – 1000 nm at 1 nm intervals and at a resolution of 1 @ FWHM.

Absolute photon flux calibration detector Three photodiode light trap photodetector QED-200-14526 (Calibrated absolute photometer for quantum efficiency measurements)

Calibration of the FPI Hyperspectral Imager 3(5)

The calibration measurement for the FPI hyperspectral image sensor is performed by recording for each selected air gap value the images of the RGB image sensor for the same spectral range and at the same spectral step and slit width as in the calibration of the spectral photon flux.

Calibration of the FPI Hyperspectral Imager 4(5)

Because the spectral photon flux $\Phi_{ph}(\lambda)$ is known it is possible determine for hyperspectral image sensor total spectral response i.e. product $K_{ADU}T_{FPI}(\lambda, d_{gap})\cdot T_{sys}(\lambda)\cdot \eta(\lambda) = S_{sys}(\lambda)$ for R-, G-, and B-pixels

$$
S_{sys}(\lambda) = \frac{K_{ADU} \cdot \eta_R(\lambda) T_{FPI}(\lambda, d_{gap}) T_{sys}(\lambda) \Phi_{ph}(\lambda)}{\Phi_{ph}(\lambda)} = K_{ADU} \cdot \eta_R(\lambda) T_{FPI}(\lambda, d_{gap}) T_{sys}(\lambda)
$$

The system gain K_{ADU} is the total gain of the image sensor in units ADU/electrons which can be determined using the mean-variance method. The sensitivity in equation above is given in absolute units ADU/photons.

Typical result of a FPI Hyperspectral Imager Calibration

•Measured total spectral sensitivity of R-, G-, and B-pixels at air gap value 1400 nm •Spectral resolution is 7 – 9 nm @ FWHM

•Measured total spectral sensitivity at spectral peak of FPI order n+2 at air gap value 1400 nm.

•The total spectral sensitivity is derived as a weighted sum of the R-, G-, and B-pixel sensitivities plotted on the left.

•The weights were taken from R-matrix for FPI air gap 1400nm. R-pixel weight $=$ -0.154, G-pixel weight $=$ 2.098 and B-pixel weight = -2.184

Wavelength/[nm]

SNR estimation for the FPI Hyperspectral Imager

The total spectral sensitivity function for one specific spectral band representing one FPI order at a fixed FPI air gap can be expressed with Equation

$$
I(\lambda) = (R_{Rn+2} \cdot \eta_R(\lambda) + R_{Gn+2} \cdot \eta_G(\lambda) + R_{Bn+2} \cdot \eta_B(\lambda)) \cdot T_{FPI}(\lambda, d_{gap}) T_{sys}(\lambda)
$$

If we assume a constant signal over the whole spectral range we get for the signal at the spectral peak of FPI order n+2 (λ_{n+2}) S_{n+2}

$$
S_{n+2} = \int_{\lambda_{n+2}-\Delta\lambda}^{\lambda_{n+2}+\Delta\lambda} (R_{Rn+2} \cdot \eta_R(\lambda) + R_{Gn+2} \cdot \eta_G(\lambda) + R_{Bn+2} \cdot \eta_B(\lambda)) \cdot T_{FPI}(\lambda, d_{gap}) T_{sys}(\lambda) \Phi_{ph}(\lambda) d\lambda
$$

The square of the noise $(N_{n+2})^2$ can be estimated with the following

$$
N_{n+2}^{2} = \int_{\lambda_{\min}}^{\lambda_{n+2}-\Delta\lambda} ((R_{Rn+2} \cdot \eta_{R}(\lambda) + R_{Gn+2} \cdot \eta_{G}(\lambda) + R_{Bn+2} \cdot \eta_{B}(\lambda)) \cdot T_{FPI}(\lambda, d_{gap}) T_{sys}(\lambda) \Phi_{ph}(\lambda))^{2} d\lambda +
$$

$$
\int_{\lambda_{\max}}^{\lambda_{\max}} ((R_{Rn+2} \cdot \eta_{R}(\lambda) + R_{Gn+2} \cdot \eta_{G}(\lambda) + R_{Bn+2} \cdot \eta_{B}(\lambda)) \cdot T_{FPI}(\lambda, d_{gap}) T_{sys}(\lambda) \Phi_{ph}(\lambda))^{2} d\lambda
$$

Where $\Delta\lambda$ is width of the spectral peak defined in such a way that the signal is contained in the range λ_{n+2} - $\Delta\lambda$ - $\lambda_{n+2}+\Delta\lambda$. The relevant spectral range $\lambda_{\min} \leq \lambda \leq \lambda_{\max}$ is determined with long and short pass filters. The Signal-to-Noise-Ratio (SNR_{n+2}) can now be expressed as

$$
SNR_{n+2} = \frac{S_{n+2}}{N_{n+2}}
$$

Example of the SNR estimation for the FPI Hyperspectral Imager

- Simulated peak wavelengths and SNR at the highest FPI order used as a function of the FPI air gap. The spectral band is limited to 500 – 900 nm with filters.
- At low FPI air gap values (100 550 nm) there is only one FPI order wavelength and the SNR value is large.
- **The SNR value drops near the air** gap values at which a spectral peak is appearing at the edges of the long or short pass filter pass band.

Devices built based on the piezo-FPIs

- **Chemical Imager (1-2.5 µm)**
	- Malinen, J. et.al., "Comparative performance studies between tunable filter and pushbroom chemical imaging systems", Proc. SPIE 7680 (2010).
- **Handheld hyperspectral imager (400-700 nm)**
	- Saari, H. et.al., "Hand-Held Hyperspectral Imager", Proc. SPIE 7680 (2010).
- **Light-weight hyperspectral imager for UAVs (500-900 nm)**
	- Saari, H. et.al., "Novel Hyperspectral Imager for Lightweight UAVs", Proc. SPIE 7668 (2010)
- **Handheld hyperspectral imager for remote sensing, food quality and medical applications**
	- Saari, H. et.al. Handheld spectral imager for remote sensing, food quality and medical applications. Proceedings of Finnish Remote Sensing Days 3.-4.11.2010.

Applications

- The light weight and framing imaging mode enable totally new applications for the hyperspectral imaging because cost effective UAVs can be used to acquire data.
- The remote sensing applications that can benefit from the new UAV instrument include precision agriculture, forestry, natural water monitoring applications.
- In space the need of compact hyperspectral imager has been also been identified and the new technology to manufacture RGB-type pixelized multispectral image sensors for wide spectral range including IR enables the development of a highly compact hyperspectral imager for SWIR (1.0 – 3.0 µm) range using MCT detector & multispectral filter in combination of Fabry-Perot interferometer.
- The hyperspectral imaging has been used in medical imaging, accurate color measurements, pharmaceutical manufacturing, diagnostic test analysis equipment, art restoration, archaeology etc.
- The presented new concept has potential to offer hyperspectral imaging system at a much lower cost level opening many applications in which it has been previously blocked by the cost of hardware.

Conclusions and future plans

- The Fabry-Perot Interferometer technology has been developed at VTT to level that it can be used in hyperspectral imagers
- In many applications it is beneficial to produce megapixel 2D spatial images with a single exposure at a few selected wavelength bands instead of 1D spatial and all spectral band images like in push broom instruments.
- In this spectrometer the multiple orders of the Fabry-Perot Interferometer are used at the same time matched to the sensitivities of the multispectral image sensor wavelength channels.
- The F-number of the spectral camera can be as low as 1.0 for cases were full spectral data cube is to be measured.
- The size ($<$ 65 mm x 65 mm x 120 mm), weight ($<$ 400 g) and power consumption ($<$ 3 W) of the FPI hyperspectral spectrometer is compatible with the light weight UAV platforms.
- The Finnish Aalto-1 Nanosatellite Payload will be based on the MEMS FPI hyperspectral imager.

Contacts

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Additional slides on the-state-of-the-art of the hyper and multispectral imaging technology and on planned UAV applications of Fabry-Perot Interferometer spectral imager

State-of-the-art in multi&hyperspectral imaging

- New multispectral technologies are being developed by companies like Ocean Optics, Silios, etc.
- The Rotating Filter Wheel (RFW) Multispectral Camera technology has developed with small steps during recent years.
- The new opportunities is offered by the Dichroic Filter Array (DFA) Multispectral Camera technology presented by Ocean Optics at the SPIE conference "Imaging, Manipulation, and Analysis of Biomolecules, Cells, and Tissues VIII" SPIE Vol.7568.
- VTT has developed MEMS Fabry-Perot Interferometers for the visible wavelength range. This technology is planned to be used in the Finnish Aalto-1 nanosatellite for hyperspectral remote sensing.
- The combination of a MEMS FPI and a dichroic filter array would enable to build a hyperspectral imager whose spectral bands could be tuned to various applications.

Rotating Filter Wheel (RFW) Multispectral Camera

- **Multispectral imaging has traditionally** been performed with rotating filter wheel.
- **If the wavelength bands required for the** application are known the RFW multispectral imager is a straight forward solution.
- The disadvantages of the RFW concept are
	- \triangleright Tuning of the spectral bands is not possible
	- ¾The spectral bands are registered at different times
	- \triangleright The miniaturization is challanging because of the filter wheel mechanism.

Figure 2. RFW pass bands overlaid with the key blood oxygenation curves of the initial application. Note the >75% pass band for the filters (Filter1-Filter4), as well as the visible blocking filter (VIS). Also shown are molar extinction curves in cm⁻¹/(moles/liter)

Ref. Eichenholz, J.M., et.al., "Real time Megapixel Multispectral Bioimaging", Proc. SPIE 7568 (2010).

Dichroic Filter Array (DFA) Multispectral Camera

- The physical size of the DFA is 35 mm x 23 mm and there are 3500x2500 individual filters on the DFA. The pixel pitch is 10 µm x 10 ȝm.
- The image of a target is formed on the DFA surface and the Microscope objective forms an image of the DFA on the Camera sensor.
- The advantages of DFA camera are
	- \triangleright The spectral bands are registered simultaneously
	- \triangleright No moving parts
- The disadvantages of the DFA concept are
	- \triangleright Tuning of the spectral bands is not possible
	- \triangleright The miniaturization is challenging because of relay optics required for imaging the

Figure 5. (a) Bayer like pattern and (b) microscope image of the dichroic filter array.

The physical size of the DFA is 35 mm x 23 mm. There are 8.75 Million (3500x2500) individual filters on each DFA. Each individual pixel is 10 um x 10 um on a 10 um center to center spacing with a 1 micron border around the edge of each pixel resulting in an active area of 8 um x 8 um. A microscope transmission image of a small section of the DFA is shown above in Figure 5b.

DFA to the image sensor. Ref. Eichenholz, J.M., et.al., "Real time Megapixel Multispectral Bioimaging", Proc. SPIE 7568 (2010).

Hyperspectral imager concept based on combining a Dichroic Filter Array with Fabry-Perot Interferometer

Application of spectral imaging in crop farming Application of spectral imaging in crop farming - Information flow is marked with numbers Information flow is marked with numbers

Application of spectral imaging in forestry applications-**Information flow is marked with numbers Information flow is marked with numbers**

Aalto-1 Nanosatellite Payload Overview

- A miniature Hyperspectral Imager based on a tunable Fabry-Pérot interferometer
- Joint project between Aalto-university and VTT Technical Research Centre of Finland
- The spectrometer module is built and developed by VTT Technical Research Centre of Finland
- The spectral imager is accompanied by a high resolution digital camera
- The smallest hyperspectral imager to be used in a satellite

Spectral imaging for the monitoring of Wine leave health status

- Wine grapes are robust plants that can live more than 100 years but, depending on the atmospheric conditions, they may be attacked by several different plagues or diseases along their lives, or even by hailstorms. And all these problems affect in different ways to the quality of the grapes growing on those wines and, consequently in the long run, to the wine.
- **Spectral imaging experiments were** planned to detect Mildew on Wine leaves
- **Downy Mildew is a disease that can be** extremely serious in grapes and will cause severe crop loss. The fungus Plasmopara viticola causes downy mildew.

Case 2: Spectral imaging in clinical processes especially brain surgery 1(2)

Cedip IR camera

MEDICAL INFRARED

operation microscope (Zeiss Pentero)

Infrared thermal Image of deep vein Thrombphlebitu on the left leg

<http://www.infraredcamerasinc.com>

<http://www.flir.com/thermography/eurasia/en/> 45

Case 2: Spectral imaging in clinical processes especially brain surgery 2(2)

- **In the MEDI-IMAGING** project Fabry-Perot Interferometer Spectral camera will be integrated to the Zeiss Pentero brain surgery microscope.
- The spectral range used in the study is 400 – 1000 nm.

The unique TRIO 620 is easy to attach

Ergonomics and freedom of movement are unchanged

The spectral camera is planned to be integrated to the Zeiss pentero brain surgery microscope at the Kuopio **University Hospital**

